

UNIVERSITY OF SURREY<sup>©</sup>

Faculty of Engineering and Physical Sciences

Department of Mathematics

Undergraduate Programmes in Mathematical Studies

Module MAT3008 — 15 Credits

LAGRANGIAN AND HAMILTONIAN DYNAMICS

Level HE3 Examination

Time allowed: Two hours

Semester 1, 2011/12

Answer **THREE** questions only

If a candidate attempts more than **THREE** questions only the best **THREE** questions will be taken into account.

Each question carries 25 marks.

Approved calculators are allowed.

*Additional material:*

1 handout

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**Question 1**

A simple pendulum comprises of a particle of mass  $m$  attached to the end of a light stiff rod of length  $l$ . The simple pendulum is in a constant gravitational field, with gravity acting downwards. The massless pivot  $P$  executes an anticlockwise circular motion on a circumference with centre  $O$  and radius  $a$  with constant angular velocity  $\omega$  in a vertical plane, so that at time  $t$ ,  $OP$  makes an angle  $\omega t$  with the downward drawn vertical. Hence the displacement of the pivot  $P$  is

$$x_p = a \sin \omega t, \quad y_p = a \cos \omega t,$$

where  $x_p$  and  $y_p$  are its cartesian coordinates, relative to axes  $(Ox, Oy)$  with the  $Oy$  direction vertically downwards.

- (a) Show that the Lagrangian for the motion of the simple pendulum is

$$L = \frac{ma^2}{2}\omega^2 + \frac{ml^2}{2}\dot{\theta}^2 + mga \cos(\omega t) + mgl \cos \theta + ml\omega\dot{\theta} \cos(\theta - \omega t),$$

where  $\theta$  is the angle made by the stiff rod with the downward vertical,  $g$  is the constant acceleration due to gravity, and the dots denote differentiation with respect to time. [8]

- (b) Show that an equivalent Lagrangian for the system is given by

$$\bar{L} = \frac{ml^2}{2}\dot{\theta}^2 + ml\omega^2 \cos(\theta - \omega t) + mgl \cos \theta.$$

[5]

- (c) From  $\bar{L}$ , find the Lagrangian equation of motion. [4]

- (d) Assume now that  $\omega$  and  $\theta$  remain small throughout the motion of the pendulum, so that, in the equation of motion, we can neglect all the terms of order  $\omega^2\theta$  or smaller. Linearize the system under this assumption and find its general solution under the hypothesis  $\frac{g}{l} \neq \omega^2$ . [8]

**Question 2**

The vector angular momentum about the origin  $O$  of a particle of unit mass at position  $\mathbf{r}$ , and moving with linear momentum  $\mathbf{p} = \dot{\mathbf{r}}$  in a central force field having the potential  $V = V(r)$ , is given by

$$\mathbf{J} = \mathbf{r} \times \mathbf{p} = \mathbf{r} \times \dot{\mathbf{r}},$$

where  $r$  is the distance of the particle from the fixed centre of force  $O$ , and the dots denote differentiation with respect to time.

(a) Show that the time derivative  $\dot{\mathbf{J}}$  is zero. [2]

(b) Thus show that the particle moves on the plane generated by the vectors  $\mathbf{r}$  and  $\mathbf{p} = \dot{\mathbf{r}}$ . [6]

(c) Introducing polar coordinates  $(r, \theta)$  on this plane, show that the total energy of the particle is given by

$$E = \frac{1}{2}(\dot{r}^2 + r^2\dot{\theta}^2) + V(r),$$

and the magnitude of its angular momentum is given by

$$J = r^2\dot{\theta}.$$

[4]

(d) By using  $J = r^2\dot{\theta}$  show that the energy takes the form

$$E = \frac{1}{2}\dot{r}^2 + \frac{J^2}{2r^2} + V(r) = \frac{1}{2}\dot{r}^2 + U(r),$$

where  $U(r)$  is the effective potential. [2]

(e) Take the particular case in which the above particle moves in a potential having the form  $V = \frac{k}{2}r^2$ , where  $k$  is a positive constant. Show that the effective potential has a minimum at  $r_e = \left(\frac{J^2}{k}\right)^{1/4}$ , where  $r_e$  is such that  $E = U(r_e)$  and therefore  $\dot{r} = 0$ . [6]

(f) Thus show that the particle moves on a circle about the origin and find the period of its motion. [5]

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**Question 3**

(a) Given two sufficiently regular functions  $f(\mathbf{q}, \mathbf{p}, t)$  and  $g(\mathbf{q}, \mathbf{p}, t)$ , where  $\mathbf{q} \equiv (q_1, q_2, \dots, q_n)$  and  $\mathbf{p} \equiv (p_1, p_2, \dots, p_n)$ , define their Poisson bracket  $[f, g]$ . [1]

(b) Consider a sufficiently regular function  $f(\mathbf{q}, \mathbf{p}, t)$ , with  $(\mathbf{q}, \mathbf{p})$  as above. Give the definition for  $f(\mathbf{q}, \mathbf{p}, t)$  to be a first integral for the motion of the system with Hamiltonian  $H = H(\mathbf{q}, \mathbf{p}, t)$ . [1]

(c) Show that if a time independent function  $f(\mathbf{q}, \mathbf{p})$  is a first integral for a Hamiltonian system with Hamiltonian  $H = H(\mathbf{q}, \mathbf{p}, t)$ , then its Poisson bracket with the Hamiltonian vanishes. [2]

(d) Given two sufficiently regular functions  $f(\mathbf{q}, \mathbf{p}, t)$  and  $g(\mathbf{q}, \mathbf{p}, t)$ , by using the Jacobi identity, show that

$$\frac{d}{dt}[f, g] = \left[\frac{df}{dt}, g\right] + \left[f, \frac{dg}{dt}\right]. \quad [10]$$

(e) Consider the type-one generating function  $F_1(Q, q) = \lambda q^2 \cot Q$ , where  $\lambda$  is a constant.

i) Find the canonical transformation generated by the above generating function from the  $(Q, P)$  representation to the  $(q, p)$  representation, and verify directly that it is canonical. [4]

ii) Then consider the Hamiltonian in the  $(q, p)$  representation given by  $H(q, p) = \frac{p^2}{2m} + \frac{\omega^2 q^2}{2m}$ , where  $\omega$  and  $m$  are positive constants. Find the new Hamiltonian  $K(Q, P)$  in the  $(Q, P)$  representation and then choose  $\lambda$  so as to make this new Hamiltonian independent of  $Q$ . [4]

iii) Hence find the motion in both the representation  $(Q, P)$  and  $(q, p)$ . [3]

**Question 4**

Consider the Lagrangian

$$L = \frac{\dot{q}^2}{2(1+q)^2} - \ln(1+q), \quad q \geq 0.$$

- (i) Show that the corresponding Hamiltonian function is given by

$$H(q, p) = (1+q)^2 \frac{p^2}{2} + \ln(1+q)$$

and find Hamilton's equations of motion. [5]

- (ii) Find the canonical transformation generated by a generating function of the type  $F_3(p, Q) = -p(e^Q - 1)$  and find the transformed Hamiltonian function  $K(P, Q)$ . [5]

- (iii) By using the Hamiltonian  $K(P, Q)$  found in (ii), solve the equations of motion with initial conditions  $q(0) = q_0 \geq 0$ ,  $p(0) = p_0$ . [6]

- (iv) Solve the equations of motion found in (i) by using the method of Hamilton-Jacobi. [9]

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