# ERGODIC OPTIMIZATION FOR GENERIC CONTINUOUS FUNCTIONS

### IAN D. MORRIS

ABSTRACT. Given a real-valued continuous function f defined on the phase space of a dynamical system, an invariant measure is said to be *maximizing* if it maximises the integral of f over the set of all invariant measures. Extending results of Bousch, Jenkinson and Brémont, we show that the ergodic maximizing measures of a generic continuous function have the same properties as generic ergodic measures.

### 1. INTRODUCTION

Let  $T: X \to X$  be a continuous transformation of a compact metric space. Let  $\mathcal{M}_T$  denote the set of *T*-invariant Borel probability measures on *X*, and let  $\mathcal{E}_T \subseteq \mathcal{M}_T$  denote the set of ergodic measures. We equip both of these sets with the weak-\* topology. For each continuous  $f: X \to \mathbb{R}$  we define the maximum ergodic average

$$\beta(f) = \sup_{\mu \in \mathcal{M}_T} \int f \, d\mu = \sup_{x \in X} \limsup_{n \to \infty} \frac{1}{n} \sum_{k=0}^{n-1} f(T^k x)$$

and the set of all maximizing measures of f,

$$\mathcal{M}_{\max}(f) := \left\{ \mu \in \mathcal{M}_T \colon \int f \, d\mu = \beta(f) \right\}$$

The study of the functional  $\beta$  and sets  $\mathcal{M}_{\max}(f)$  has been termed *ergodic optimisation*, and has attracted some recent research interest [2, 3, 4, 6, 5, 7, 9, 13, 16]. In this note we examine the behaviour of the set  $\mathcal{M}_{\max}(f)$  when f ranges over a dense  $G_{\delta}$  subset of C(X).

We briefly summarise some existing results. In [4], T. Bousch and O. Jenkinson showed that in the case where  $T: X \to X$  is an expanding map of the circle, there is a dense  $G_{\delta}$  subset of C(X) for which  $\mathcal{M}_{\max}(f)$  is a singleton set containing a fully supported measure. In [5] J. Brémont showed under a more general hypothesis that, additionally, there is a dense  $G_{\delta}$  subset of C(X) for which the unique element of  $\mathcal{M}_{\max}(f)$  has zero entropy. In the case of an expanding map of the circle, zero entropy and full support are *generic* properties of elements of  $\mathcal{M}_T$  in the sense of Baire category. In this note we extend and unite these results by showing that the properties of the ergodic elements of  $\mathcal{M}_{\max}(f)$  for generic  $f \in C(X)$  are the same as the properties of generic elements of  $\overline{\mathcal{E}_T}$ . We prove the following:

**Theorem 1.1.** Suppose that  $\mathcal{U}$  is a dense open subset of  $\overline{\mathcal{E}_T}$ . Then the set

$$U := \left\{ f \in C(X) \colon \overline{\mathcal{E}_T} \cap \mathcal{M}_{\max}(f) \subseteq \mathcal{U} \right\}$$

is open and dense in C(X). Conversely, if  $U \subseteq C(X)$  is open and dense, then the set

$$\mathcal{U} := \mathcal{E}_T \cap \bigcup_{f \in U} \mathcal{M}_{\max}(f)$$

is open and dense in  $\mathcal{E}_T$ .

Since  $\mathcal{E}_T$  is a dense  $G_{\delta}$  subset of the compact metric space  $\overline{\mathcal{E}_T}$  it is a Baire space, and we may deduce

**Corollary 1.2.** Suppose that  $\mathcal{U}$  is a dense  $G_{\delta}$  subset of  $\mathcal{E}_T$ . Then the set  $U := \{ f \in C(X) \colon \mathcal{E}_T \cap \mathcal{M}_{\max}(f) \subseteq \mathcal{U} \}$ 

a dense  $G_{\delta}$  subset of C(X). Conversely, if  $U \subseteq C(X)$  is a dense  $G_{\delta}$ , then

$$\mathcal{U} := \mathcal{E}_T \cap \bigcup_{f \in U} \mathcal{M}_{\max}(f)$$

is a dense  $G_{\delta}$  subset of  $\mathcal{E}_T$ .

The following generalisation of results of Bousch-Jenkinson [4, Theorem C] and Brémont [5, Theorem 1.2] follows directly.

**Corollary 1.3.** Suppose that  $T: X \to X$  satisfies Bowen's specification property. Then there is a dense  $G_{\delta}$  set  $Z \subseteq C(X)$  such that for every  $f \in Z$ ,  $\mathcal{M}_{\max}(f)$  is a singleton set containing a measure of zero entropy which has support equal to X and is not strongly mixing.

*Proof.* K. Sigmund proves in [15] that in this context  $\overline{\mathcal{E}_T} = \mathcal{M}_T$  and a dense  $G_{\delta}$  subset of  $\mathcal{M}_T$  exists in which every measure has zero entropy and full support and is not strongly mixing. Applying Theorem 1.2 yields the result.

We suggest the following further application of Theorem 1.1. Let  $X = \mathbb{R}/\mathbb{Z}$ , let  $T: X \to X$  be the transformation  $Tx = 2x \mod 1$ . T. Bousch, O. Jenkinson and others have shown that elements of  $\mathcal{E}_T$  which are supported in a semi-circle - termed *Sturmian measures* - arise as maximising measures for several classes of continuous functions [1, 2, 11]. It is easily seen that the set of Sturmian measures is a closed subset of  $\overline{\mathcal{E}_T} = \mathcal{M}_T$  having empty interior, and so by Theorem 1.1 it follows that the set of continuous functions having a Sturmian maximising measure is nowhere dense in C(X).

## 2. Preliminaries

We begin with the following simple result:

**Lemma 2.1.** Let  $\mu \in \mathcal{M}_T$  and  $\nu \in \mathcal{E}_T$ , and suppose that there is  $\kappa < 2$  such that  $|\int \psi \, d\mu - \int \psi \, d\nu| \leq \kappa |\psi|_{\infty}$  for every  $\psi \in C(X)$ . Then there exist  $\hat{\mu} \in \mathcal{M}_T$  and  $\lambda \in (0,1)$  such that  $\mu = (1-\lambda)\hat{\mu} + \lambda\nu$ .

*Proof.* We begin by showing that  $\mu$  and  $\nu$  are not mutually singular. Let  $\delta < (2 - \kappa)/4$ . If  $\mu \perp \nu$ , choose closed sets  $K_1, K_2 \subseteq X$  with  $\min\{\mu(K_1), \nu(K_2)\} > 1 - \delta$  and  $K_1 \cap K_2 = \emptyset$ , and let  $\psi \in C(X)$  with  $|\psi|_{\infty} = 1$ ,  $\psi^{-1}\{1\} = K_1$  and  $\psi^{-1}\{-1\} = K_2$ . We then have

$$\int \psi \, d\mu - \int \psi \, d\nu \ge \mu(K_1) - \mu(X \setminus K_1) + \nu(K_2) - \nu(X \setminus K_2) > 2 - 4\delta > \kappa$$

contradicting the hypothesis of the lemma.

In view of this we deduce from the Lebesgue decomposition theorem that there exist  $\hat{\mu}, \hat{\nu} \in \mathcal{M}$  and  $\lambda \in (0, 1)$  such that  $\mu = (1 - \lambda)\hat{\mu} + \lambda\hat{\nu}$ , where  $\hat{\mu} \perp \nu$  and  $\hat{\nu} \gg \nu$ . A standard argument such as in e.g. [17] shows that necessarily  $\hat{\mu}, \hat{\nu} \in \mathcal{M}_T$ , and since  $\nu$  is ergodic it follows that  $\hat{\nu} = \nu$ .

The following key result is due to J. Brémont. A weaker version is implicit in [12, Proposition 1]; a similar result occurred in a preprint version of [14] but was not included in the published version. T. Bousch has remarked that this result resembles a theorem of I. Ekeland [8, Theorem 1.1].

**Lemma 2.2** ([5]). Let  $f \in C(X)$  and  $\mu \in \mathcal{M}_T$ , and let  $\beta(f) = \int f d\mu + \varepsilon \delta$  with  $\varepsilon, \delta \geq 0$ . Then there exists  $g \in C(X)$  and  $\nu \in \mathcal{M}_{\max}(g)$  such that  $|f - g|_{\infty} \leq \delta$  and such that  $|\int \psi d\mu - \int \psi d\nu| \leq \varepsilon |\psi|_{\infty}$  for every  $\psi \in C(X)$ .

We deduce the following

**Proposition 2.3.** Let  $f \in C(X)$  and  $\varepsilon > 0$ . If  $\nu \in \mathcal{E}_T$  has  $\beta(f) - \int f \, d\nu < \varepsilon$  then there exists  $g \in C(X)$  such that  $|f - g|_{\infty} < \varepsilon$  and  $\nu \in \mathcal{M}_{\max}(g)$ .

Proof. By the preceding lemma there exist  $g \in C(X)$  and  $\mu \in \mathcal{M}_{\max}(g)$  such that  $|f - g|_{\infty} < \varepsilon$  and  $|\int \psi \, d\mu - \int \psi \, d\nu| \le |\psi|_{\infty}$  for every  $\psi \in C(X)$ . It follows from Lemma 2.1 that  $\mu = (1 - \lambda)\hat{\mu} + \lambda\nu$  for some  $\lambda \in (0, 1)$  and  $\hat{\mu} \in \mathcal{M}_T$ , whence  $\int g \, d\nu = \beta(f)$  and  $\nu \in \mathcal{M}_{\max}(g)$  as required.  $\Box$ 

Finally we recall the following result due to O. Jenkinson [10].

**Proposition 2.4.** Let  $\mu \in \mathcal{E}_T$ . Then there exists  $h \in C(X)$  such that  $\mathcal{M}_{\max}(h) = \{\mu\}$ .

### 3. Proof of Theorem 1.1

Theorem 1.1 may be deduced from the following four lemmas, some of which may be of individual interest.

*Remarks.* Lemma 3.1 is of a standard type, being similar to parts of the proofs of [7, Proposition 10], [9, Theorem 3.2] and [13, Theorem 1]. Lemma 3.3 generalises a result of J. Brémont [5, Proposition 2.1].

**Lemma 3.1.** Let  $\mathcal{U}$  be an open subset of  $\overline{\mathcal{E}_T}$ , and define

$$U = \left\{ f \in C(X) \colon \mathcal{M}_{\max}(f) \cap \overline{\mathcal{E}_T} \subseteq \mathcal{U} \right\}.$$

Then U is open in C(X).

Proof. Let  $(f_n)_{n\geq 1}$  be a convergent sequence in  $C(X) \setminus U$  with limit  $f \in C(X)$ , and take  $\mu_n \in \mathcal{M}_{\max}(f_n) \cap (\overline{\mathcal{E}_T} \setminus \mathcal{U})$  for each n. Since  $\overline{\mathcal{E}_T} \setminus \mathcal{U}$  is weak-\* compact we may take a subsequence  $n_r$  so that  $\mu_{n_r} \to \mu \in \overline{\mathcal{E}_T} \setminus \mathcal{U}$ . For every  $\nu \in \mathcal{M}_T$  and  $r \geq 1$  we have

$$\int f \, d\nu - |f - f_{n_r}|_{\infty} \le \int f_{n_r} \, d\nu \le \int f_{n_r} \, d\mu_{n_r} \le \int f \, d\mu_{n_r} + |f - f_{n_r}|_{\infty}$$

yielding  $\int f \, d\nu \leq \int f \, d\mu$ . Since  $\nu$  is arbitrary we deduce that  $\mu \in (\mathcal{M}_{\max}(f) \cap \overline{\mathcal{E}_T}) \setminus \mathcal{U}$  and therefore  $f \in C(X) \setminus U$ . We conclude that  $C(X) \setminus U$  is closed and consequently U is open.  $\Box$ 

**Lemma 3.2.** Let  $U \subseteq C(X)$  be open, and define

$$\mathcal{U} := \mathcal{E}_T \cap \bigcup_{f \in U} \mathcal{M}_{\max}(f)$$

Then  $\mathcal{U}$  is open in  $\mathcal{E}_T$ .

Proof. Let  $\mu \in \mathcal{U}$ , and let  $f \in U$  such that  $\mu \in \mathcal{M}_{\max}(f)$ . Choose  $\varepsilon > 0$  such that  $|f - g|_{\infty} < \varepsilon$  implies  $g \in U$ , and let  $\mathcal{V} \subseteq \mathcal{E}_T$  be an open neighbourhood of  $\mu$  small enough that  $\beta(f) - \int f \, d\nu < \varepsilon$  for every  $\nu \in \mathcal{V}$ . If  $\nu \in \mathcal{V}$ , then it follows by Proposition 2.3 there exists  $g \in U$  such that  $\nu \in \mathcal{M}_{\max}(g)$ . We conclude that  $\mathcal{V} \subseteq \mathcal{U}$  and  $\mathcal{U}$  is an open subset of  $\mathcal{E}_T$ .

**Lemma 3.3.** Let  $\mathcal{U}$  be a dense subset of  $\mathcal{E}_T$ , and let  $U \subseteq C(X)$  be the set of all f such that  $\mathcal{M}_{\max}(f)$  is a singleton set containing an element of  $\mathcal{U}$ . Then U is dense in C(X).

Proof. We must show that U intersects every nonempty open  $V \subseteq C(X)$ . Consider such a V, and define  $\mathcal{V} := \mathcal{E}_T \cap \bigcup_{f \in V} \mathcal{M}_{\max}(f)$ . By Lemma 3.2,  $\mathcal{V}$  is open in  $\mathcal{E}_T$ , and it is clearly nonempty. Since  $\mathcal{U}$  is dense in  $\mathcal{E}_T$  we have  $\mathcal{U} \cap \mathcal{V} \neq \emptyset$ . Let  $\mu \in \mathcal{U} \cap \mathcal{V}$ and choose  $f \in V$  with  $\mu \in \mathcal{M}_{\max}(f)$ . Since  $\mu \in \mathcal{E}_T$  we may apply Proposition 2.4 to deduce that there exists  $h \in C(X)$  with  $\mathcal{M}_{\max}(h) = \{\mu\}$ . For each  $\delta > 0$  we clearly have  $\mathcal{M}_{\max}(f + \delta h) = \{\mu\}$  so that  $f + \delta h \in U$ . Since V is open we conclude that  $f + \delta h \in U \cap V$  for small enough  $\delta > 0$ .

**Lemma 3.4.** Let  $U \subseteq C(X)$  and define  $\mathcal{U} = \mathcal{E}_T \cap \bigcup_{f \in U} \mathcal{M}_{\max}(f)$ . If U is dense in C(X), then  $\mathcal{U}$  is dense in  $\mathcal{E}_T$ .

*Proof.* Clearly it suffices to show that  $\mathcal{U}$  intersects every nonempty open subset of  $\overline{\mathcal{E}_T}$ . Let  $\mathcal{V} \subseteq \overline{\mathcal{E}_T}$  be a such an open set. By Lemma 3.1 the set

$$V := \{ f \in C(X) \colon \mathcal{M}_{\max}(f) \cap \overline{\mathcal{E}_T} \subseteq \mathcal{V} \}$$

is open in C(X). Since  $\mathcal{V}$  is nonempty and open in  $\overline{\mathcal{E}_T}$  it contains an ergodic element  $\mu$ . By Proposition 2.4 there exists  $g \in C(X)$  such that  $\mathcal{M}_{\max}(g) = \{\mu\} \subseteq \mathcal{V}$  and thus V is nonempty. Since U is dense in C(X) it follows that  $U \cap V \neq \emptyset$  and consequently  $\mathcal{U} \cap \mathcal{V} \neq \emptyset$ .

### 4. Acknowledgements

This research was supported by EPSRC grant EP/E020801/1. The author would like to thank J. Brémont for helpful remarks.

### References

- V. Anagnostopoulou, K. Díaz-Ordaz, O. Jenkinson, C. Richard, Escape from a circle and Sturmian maximizing measures, preprint (2008).
- [2] T. Bousch, Le poisson n'a pas d'arêtes, Ann. Inst. H. Poincaré Probab. Statist. 26 (2000) 489–508.
- [3] T. Bousch, La condition de Walters, Ann. Sci. École Norm. Sup. 34 (2001) 287-311.
- [4] T. Bousch, O. Jenkinson, Cohomology classes of dynamically non-negative  $C^k$  functions, Invent. Math. 148 (2002) 207–217.
- [5] J. Brémont, Entropy and maximising measures of generic continuous functions, C. R. Math. Acad. Sci. Serié I 346 (2008) 199–201.
- [6] X. Bressaud and A. Quas, Rate of approximation of minimizing measures, Nonlinearity 20 (2007) 845–853.

- [7] G. Contreras, A. O. Lopes, P. Thieullen. Lyapunov minimizing measures for expanding maps of the circle. Ergodic Theory Dynam. Systems 21 (2001) 1379–1409.
- [8] I. Ekeland. On the variational principle. J. Math. Anal. Appl. 47 (1974) 324–353.
- [9] O. Jenkinson, Ergodic optimization, Disc. Contin. Dyn. Syst. 15 (2006) 197–224.
- [10] O. Jenkinson, Every ergodic measure is uniquely maximizing, Discrete Contin. Dyn. Syst. 16 (2006) 383–392.
- [11] O. Jenkinson, A partial order on ×2-invariant measures, Math. Res. Lett., to appear.
- [12] O. Jenkinson, I. D. Morris, Lyapunov optimizing measures for  $C^1$  expanding maps of the circle, Ergodic Theory Dynam. Systems 28 (2008) 1849–1860.
- [13] I. D. Morris, Maximizing measures of generic Hölder functions have zero entropy, Nonlinearity 21 (2008) 993–1000.
- [14] M. Pollicott and R. Sharp, Livšic theorems, maximizing measures and the stable norm, Dyn. Syst. 19 (2004) 75–88.
- [15] K. Sigmund, Generic properties of invariant measures for Axiom A diffeomorphisms, Invent. Math. 11 (1970) 99–109.
- [16] G. Yuan, B. R. Hunt, Optimal orbits of hyperbolic systems, Nonlinearity 12 (1999) 1207–1224.
- [17] P. Walters, An introduction to ergodic theory, Springer, 1981.